## 2. Any revealing of identification, appeal to evaluator and /or equations written eg, 42+8=50, will be treated as malpractice. Important Note: 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.

## Sixth Semester B.E. Degree Examination, Jan./Feb. 2021 Computers Graphics and Visualization

Max. Marks: 100 Time: 3 hrs.

TWO full auestions from each part. N

Not	e: <i>A</i>	nswer any FIVE full questions, selecting at least TWO full questions from e	acn part.	
		PART - A		
		Will the Computer Cropping? I jet and evaluin the applications of the same.	(06 Marks)	
1	a.	Discuss the physical Imaging Systems and show the process of Image form	nation with	
	b.	Discuss the physical imaging bystems and show the	(06 Marks)	
	c.	pinhole camera. With a neat sketch, discuss the major steps in Graphics Pipeline Architecture.	(08 Marks)	
		List and explain the major groups of OpenGL API functions along with an example for each		
2	a.	List and explain the major groups of openon in Transcript	(07 Marks)	
		Discuss the subtractive and Additive color models.	(05 Marks)	
	b.	What is Sierpinski Gasket? Write an OpenGL program for 3D gasket.	(08 Marks)	
	C.	what is Sterpinski Casket! Write an Open SE program		
		Discuss the logical classification of input devices with their interaction types.	3 (06 Marks)	
3	a.	What are input modes? Explain the event driven input for keyboard and window	events.	
	b.		TOTE TITOL AND	
		With a neat sketch, explain the display processor architecture along with the	display lists	
	C.	With a neat sketch, explain the display processor	(08 Marks)	
		creation and execution.		
		What are scalar, points and vectors? Explain the procedure for converting a	world object	
4	a.	What are scalar, points and vectors? Explain the procedure for	(10 Marks)	
		frame into camera or eye frame. What do you mean by affine Transformation? Discuss the basic 2D transformation.		
	b.	What do you mean by affine Transformation! Discuss the basic 2D transformations	(10 Marks)	
		Rotation, Scaling and Translation along with their matrix representations.	,	
		PART - B  Parity the composite tr	ansformation	
5	a.	Why do we require homogeneous coordinate system? Derive the composite tra	(06 Marks)	
		matrix for rotation about a fixed point $(x_f, y_f)$ by an angle $\theta$ .		
	h	Explain the 3D rotations with their representations in matrix form. Show how r	otation about	

- - Explain the 3D rotations with (06 Marks) an arbitrary axis is done.
  - How OpenGL does support transformations. Write an OpenGL program to rotate a cube about x and y axes. Use mouse buttons to select the axis of rotation. (08 Marks)
- With a neat diagram, explain the different types of views that are employed in computer \*: (10 Marks) graphics systems.
  - Derive the equations for perspective and parallel projections. Represent the same in matrix (10 Marks) form.
- What are light sources? Explain the phong lighting model. (08 Marks) 7 (06 Marks)
  - Explain any two methods for shading polygons. b. (06 Marks) How is sphere approximated? Explain.
- Explain the Cohen-Sutherland line clipping algorithm with a neat pseudo code. (10 Marks) 8 a. Digitize the line from (5, 8) to (10, 10) using the DDA algorithm. (05 Marks)
  - Write a note on Z-buffer algorithm for hidden surface removal. (05 Marks)